



Algorithm Theory

Chapter 2 Greedy Algorithms

Part II: Traveling Salesperson Problem (TSP)

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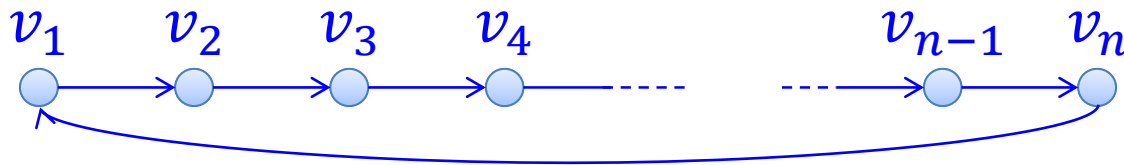
Traveling Salesperson Problem (TSP)

Input:

- Set V of n nodes (points, cities, locations, sites)
- Distance function $d: V \times V \rightarrow \mathbb{R}$, i.e., $d(u, v)$: dist. from u to v
- Distances usually symmetric, asymm. distances \rightarrow asymm. TSP

Solution:

- Ordering/permutation v_1, v_2, \dots, v_n of nodes

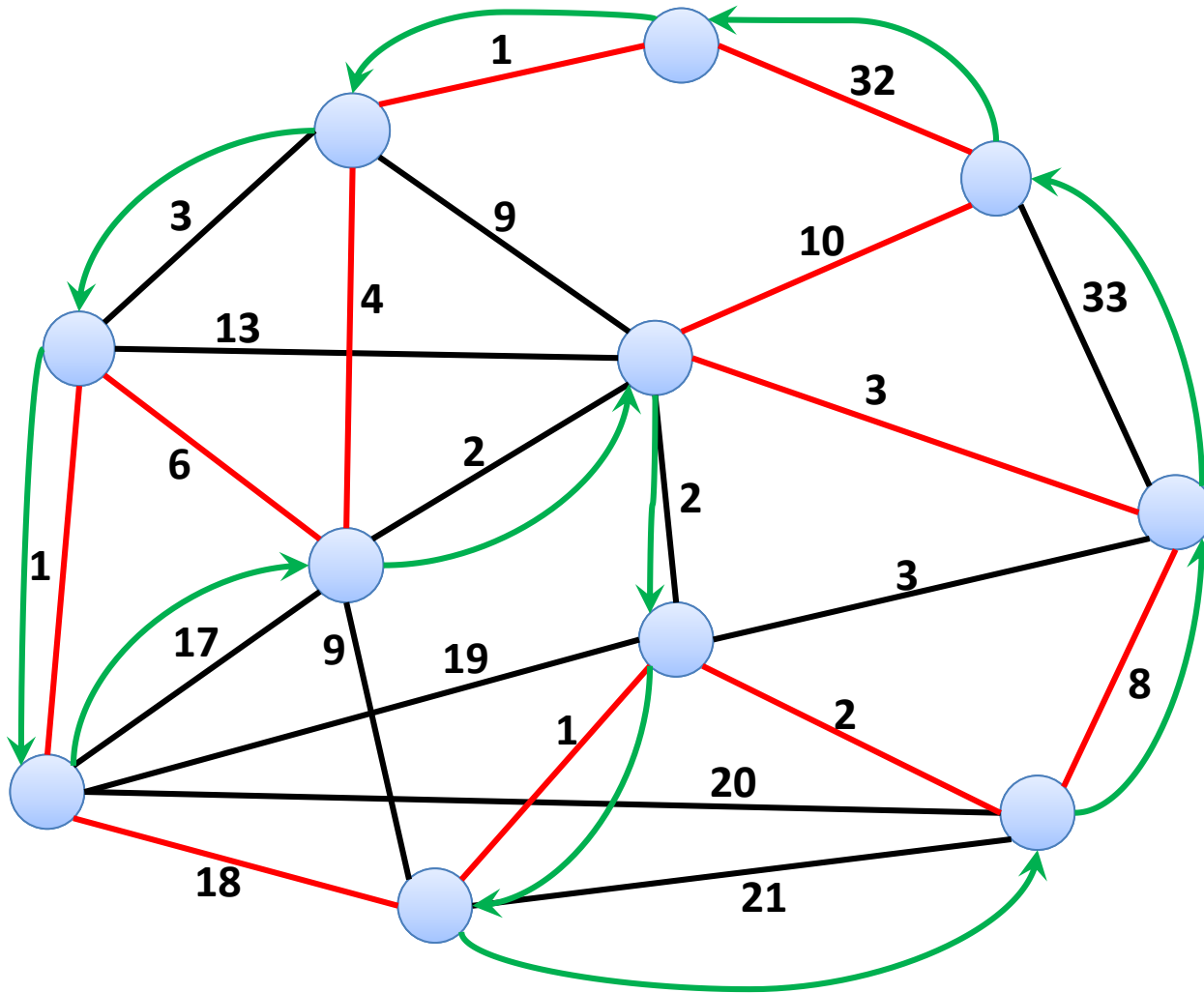


- Length of TSP path: $\sum_{i=1}^{n-1} d(v_i, v_{i+1})$
- Length of TSP tour: $d(v_n, v_1) + \sum_{i=1}^{n-1} d(v_i, v_{i+1})$

Goal:

- Minimize length of TSP path or TSP tour

Example



Greedy Algorithm

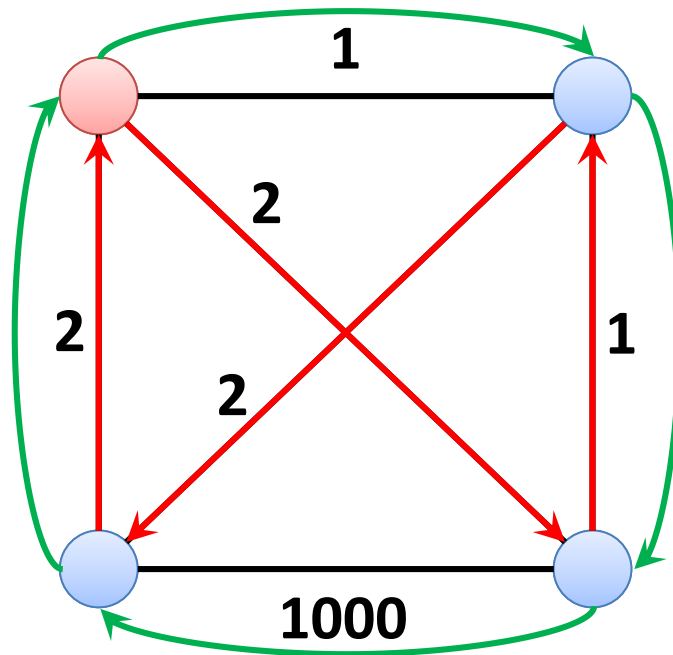
Length: 121

Optimal Tour

Length: 86

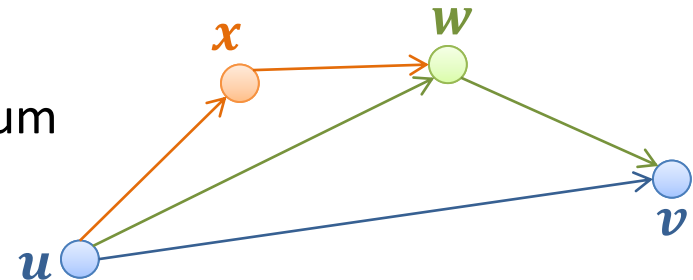
Nearest Neighbor (Greedy)

- Nearest neighbor can be arbitrarily bad, even for TSP paths



TSP Variants

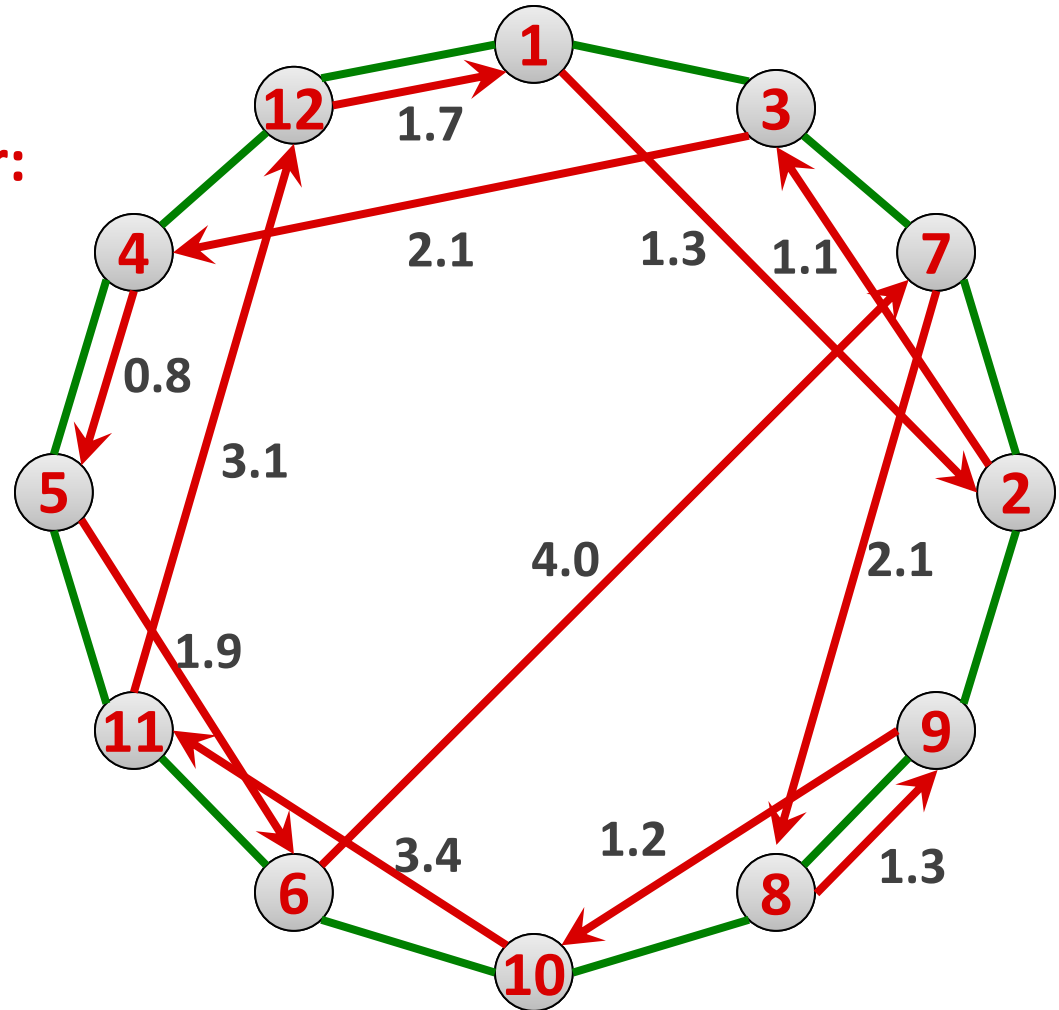
- Asymmetric TSP
 - arbitrary non-negative distance function
 - most general, nearest neighbor arbitrarily bad
 - NP-hard to get within any bound of optimum
- Symmetric TSP
 - arbitrary non-negative symmetric distance function
 - nearest neighbor arbitrarily bad
 - NP-hard to get within any bound of optimum
- Metric TSP
 - distance function defines metric space: symmetric, non-negative, triangle inequality: $d(u, v) \leq d(u, w) + d(w, v)$
 - possible to get close to optimum (we will later see factor $3/2$)
 - what about the nearest neighbor algorithm?



Metric TSP, Nearest Neighbor

Optimal TSP tour:

Nearest-Neighbor TSP tour:



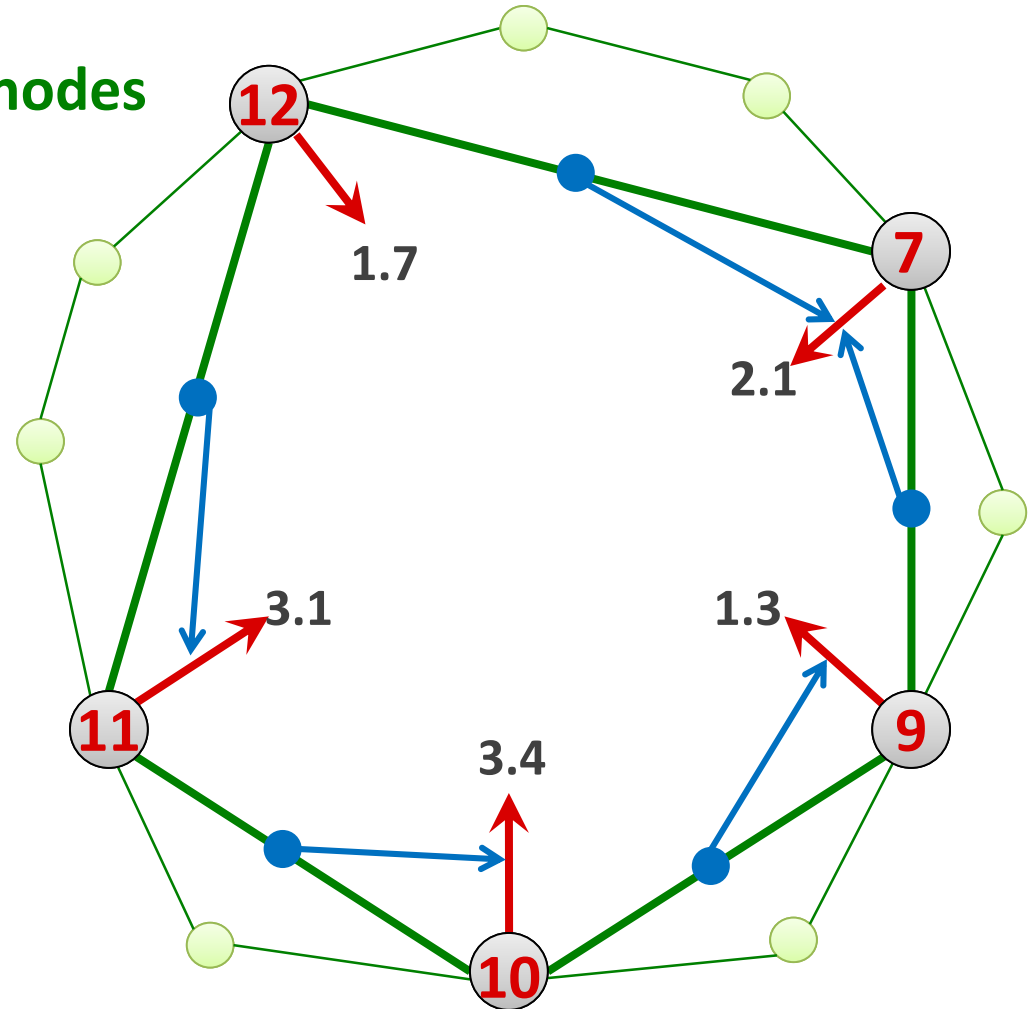
Metric TSP, Nearest Neighbor

Triangle Inequality:

optimal tour on remaining nodes

\leq

overall optimal tour



green \geq marked red

\leq OPT

marked red \leq OPT

Metric TSP, Nearest Neighbor

Analysis works in **phases**:

- In each phase, assign each optimal edge to some greedy edge
 - Cost of greedy edge \leq cost of optimal edge
- Each greedy edge gets assigned ≤ 2 optimal edges
 - At least half of the greedy edges get assigned
- At end of phase:
 - Remove nodes for which greedy edge is assigned
 - Consider optimal solution for remaining points
- **Triangle inequality:** remaining opt. solution \leq overall opt. sol.
- Cost of greedy edges assigned in **each phase \leq opt. cost**
- **Number of phases $\leq \log_2 n$**
 - +1 for last greedy edge in tour

Metric TSP, Nearest Neighbor

- Assume:

 NN: cost of greedy tour, OPT: cost of optimal tour

- We have shown:

$$\frac{\text{NN}}{\text{OPT}} \leq \underbrace{1 + \log_2 n}_{\text{approximation ratio}}$$

last red edge #phases
↙ ↘

$$(\text{NN} \leq (1 + \log_2 n) \cdot \text{OPT})$$

- Example of an **approximation algorithm**
- We will later see a $3/2$ -approximation algorithm for metric TSP